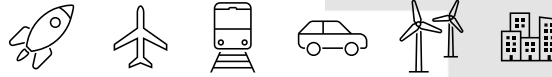


Problem statement

How to develop a multilayered composite structure with an embedded vibration control system capable of thermally driving the shape memory polymer core of this structure, so that it self-adapts to dynamic loads and maintains its static and dynamic properties within prescribed limits?

Motivation

Vibration control is of interest in multiples domains:



Background

Vibrations of a wing structure can be thermally controlled thanks to the use of a Shape Memory Polymer, but:

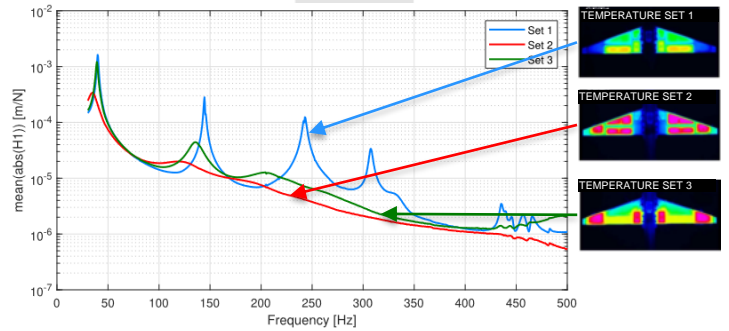
- High computational time due to 3D modeling
- Offline computations
- No adaptation to different solicitations
- Imposed external thermal configurations

► Towards a self-adaptive thermally driven multilayered composite structure for vibration control

Objectives

Develop a multilayered composite structure with an embedded vibration control system:

- Implement a reduced-order model of the multilayered composite structure;
- Formulate the vibration control law based on the thermal control of the structure's core Shape Memory Polymer;
- Conduct experiments to validate the application of the structure with the embedded vibration control system.

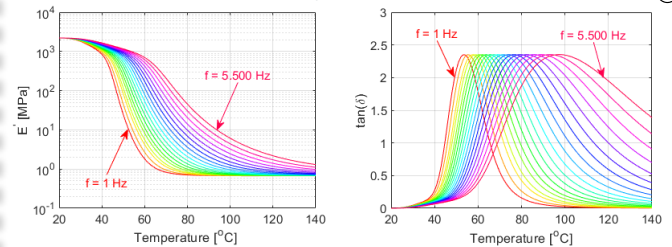


[1] P Butaud et al. In-core heat distribution for adaptive damping and stiffness tuning of composite structures. Smart Materials and Structures (2020).

A multilayered composite structure full-order model:



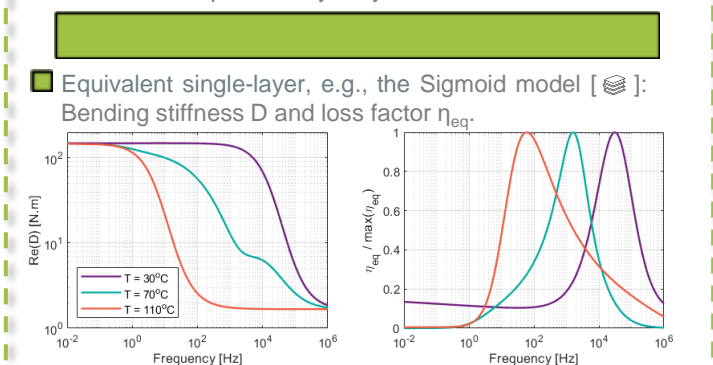
Shape Memory Polymer [2]: storage modulus E' and loss factor $\tan(\delta)$ can be thermally-driven.



[2] P Butaud et al. Sandwich structures with tunable damping properties: On the use of Shape Memory Polymer as viscoelastic core. Composite Structures (2016).

Presentation of the envisaged approach

A reduced-order model that considers the high values of the Shape Memory Polymer loss factor:

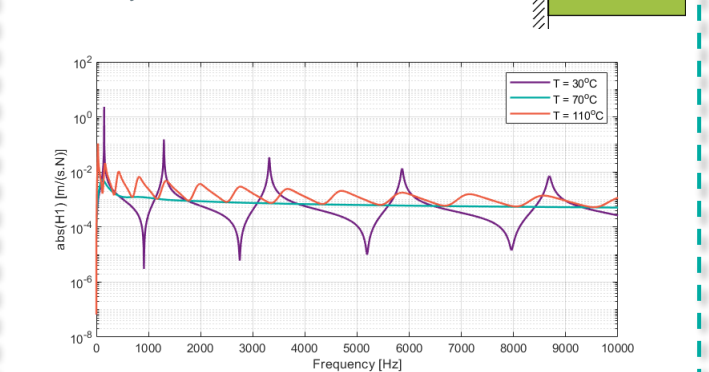


[3] U Arasan et al. A simple equivalent plate model for dynamic bending stiffness of three-layer sandwich panels with shearing core. Journal of Sound and Vibration (2021).

max(η_{eq})		
T = 30°C	T = 70°C	T = 110°C
0.0137	3.8523	0.1966

Preliminary results

The mobility of a cantilever beam:



Preliminary results indicate that we can calculate different behaviors as a function of temperature using a reduced-order model.